

REMARKS ON NEUMANN BOUNDARY VALUE PROBLEMS WITH VARIABLE EXPONENTS

Maria-Magdalena BOUREANU¹

Abstract

We are interested in elliptic problems with Neumann boundary conditions that are studied in the framework of isotropic and anisotropic spaces with variable exponents. We establish an existence and a uniqueness result concerning a problem with a general $p(\cdot)$ - Laplace type operator. In addition, we present connections to other results, some of them involving the same operator, some of them involving a general $\vec{p}(\cdot)$ - Laplace type operator.

2000 *Mathematics Subject Classification*: 35J25, 35J60, 35D30, 46E35, 35J20.

Key words: variable exponent spaces, Neumann elliptic problem, weak solutions, existence, uniqueness.

1 Introduction

We are working on Lebesgue and Sobolev spaces with variable exponent and we are concerned with the following class of elliptic problems:

$$\begin{cases} -\operatorname{div}(a(x, \nabla u)) + b(x)|u|^{p(x)-2}u = f(x, u) & \text{for } x \in \Omega, \\ a(x, \nabla u) \cdot \nu(x) = g(x, u) & \text{for } x \in \partial\Omega, \end{cases} \quad (1.1)$$

where $\Omega \subset \mathbb{R}^N$, $N \geq 2$ is a bounded domain with smooth boundary. We assume that $a : \Omega \times \mathbb{R}^N \rightarrow \mathbb{R}^N$, $a = a(x, \eta)$, is a Carathéodory function such that it is the continuous derivative with respect to η of a function $A : \Omega \times \mathbb{R}^N \rightarrow \mathbb{R}$, $A = A(x, \eta)$. More exactly, $a(x, \eta) = \nabla_{\eta} A(x, \eta)$. The mappings a and A verify the assumptions:

(A1) The equality

$$A(x, 0) = 0$$

holds for all $x \in \Omega$;

(A2) There exists a constant $c_0 > 0$ such that

$$|a(x, \eta)| \leq c_0(1 + |\eta|^{p(x)-1}),$$

¹Department of Mathematics, University of Craiova, Romania, e-mail: mmboureau@yahoo.com

for all $x \in \Omega$ and all $\eta \in \mathbb{R}^N$;

(A3) The inequality

$$0 \leq [a(x, \eta_1) - a(x, \eta_2)] \cdot (\eta_1 - \eta_2)$$

holds for all $x \in \Omega$ and all $\eta_1, \eta_2 \in \mathbb{R}^N$, with equality if and only if $\eta_1 = \eta_2$;

(A4) The inequalities

$$|\eta|^{p(x)} \leq a(x, \eta) \cdot \eta \leq p(x) A(x, \eta)$$

hold for all $x \in \Omega$ and all $\eta \in \mathbb{R}^N$;

The above set of hypotheses allows us to obtain well known operators by making some suitable choices. Indeed, for $A(x, \eta) = \frac{1}{p(x)} |\eta|^{p(x)}$ we deduce that $a(x, \eta) = |\eta|^{p(x)-2} \eta$ and for $\eta = \nabla u$ we find the $p(\cdot)$ -Laplace operator

$$\operatorname{div}(a(x, \nabla u)) = \operatorname{div} \left(|\nabla u|^{p(x)-2} \nabla u \right). \quad (1.2)$$

We get a second example of operator when we choose $A(x, \eta) = \frac{1}{p(x)} [(1 + |\eta|^2)^{p(x)/2} - 1]$, thus $a(x, \eta) = (1 + |\eta|^2)^{(p(x)-2)/2} \eta$ and for $\eta = \nabla u$ we find the generalized mean curvature operator

$$\operatorname{div}(a(x, \nabla u)) = \operatorname{div} \left((1 + |\nabla u|^2)^{(p(x)-2)/2} \nabla u \right).$$

Therefore it is no surprise that general operators described by conditions (A1) - (A4) are considered in other papers too, see for example [2, 12, 13]. In addition, nonstandard operators closely related to these appear in various situations, such is the case of classical Lebesgue-Sobolev spaces (see [11]), or the case of anisotropic Lebesgue-Sobolev spaces with variable exponent (see [1, 3]).

Our goal here is to establish an existence and a uniqueness result for problem (1.1) under some appropriate assumptions on the functions b , f and g . Since our study will be conducted in the framework of variable exponent spaces, in the next section we introduce some preliminaries.

2 Abstract framework

In the present paper, $\Omega \subset \mathbb{R}^N$ ($N \geq 2$) represents a bounded domain with smooth boundary $\partial\Omega$. We set

$$C_+(\overline{\Omega}) = \{h \in C(\overline{\Omega}) : 1 < \min_{x \in \overline{\Omega}} h(x) < \max_{x \in \overline{\Omega}} h(x) < \infty\}$$

and for all $h \in C_+(\overline{\Omega})$ we denote

$$h^+ = \sup_{x \in \Omega} h(x), \quad h^- = \inf_{x \in \Omega} h(x).$$

Also, we denote

$$h^*(x) = \begin{cases} Nh(x)/[N - h(x)] & \text{if } h(x) < N, \\ \infty & \text{if } h(x) \geq N, \end{cases}$$

and

$$h^\partial(x) = \begin{cases} (N-1)h(x)/[N-h(x)] & \text{if } h(x) < N, \\ \infty & \text{if } h(x) \geq N. \end{cases}$$

Everywhere below we consider $p \in C_+(\bar{\Omega})$. The isotropic Lebesgue space with variable exponent is defined by

$$L^{p(\cdot)}(\Omega) = \{u : u \text{ is a measurable real-valued function such that } \int_{\Omega} |u(x)|^{p(x)} dx < \infty\}$$

endowed with the Luxemburg norm

$$\|u\|_{L^{p(\cdot)}(\Omega)} = \inf \left\{ \mu > 0 : \int_{\Omega} \left| \frac{u(x)}{\mu} \right|^{p(x)} dx \leq 1 \right\}.$$

This space is a separable and reflexive Banach space (see [10, Theorem 2.5, Corollary 2.7]) and we recall a significant embedding theorem.

Theorem 2.1. ([10, Theorem 2.8]) *If $p_1, p_2 \in C_+(\bar{\Omega})$ are such that $p_1 \leq p_2$ in Ω , then the embedding $L^{p_2(\cdot)}(\Omega) \hookrightarrow L^{p_1(\cdot)}(\Omega)$ is continuous.*

Moreover, the following Hölder-type inequality

$$\left| \int_{\Omega} u(x)v(x) dx \right| \leq 2 \|u\|_{L^{p(\cdot)}(\Omega)} \|v\|_{L^{p'(\cdot)}(\Omega)}$$

holds for all $u \in L^{p(\cdot)}(\Omega)$ and $v \in L^{p'(\cdot)}(\Omega)$ (see [10, Theorem 2.1]), where we denoted by $L^{p'(\cdot)}(\Omega)$ the conjugate space of $L^{p(\cdot)}(\Omega)$, obtained by conjugating the exponent pointwise, that is, $1/p(x) + 1/p'(x) = 1$ (see [10, Corollary 2.7]).

To ease our work, we also introduce the map $\rho_{p(\cdot)} : L^{p(\cdot)}(\Omega) \rightarrow \mathbb{R}$,

$$\rho_{p(\cdot)}(u) = \int_{\Omega} |u(x)|^{p(x)} dx,$$

called the $p(\cdot)$ -modular of the $L^{p(\cdot)}(\Omega)$ space. We recall next its most important properties (see for example [9, Theorem 1.3, Theorem 1.4]). If $u \in L^{p(\cdot)}(\Omega)$, then:

$$\|u\|_{L^{p(\cdot)}(\Omega)} < 1 \quad (= 1; > 1) \quad \Leftrightarrow \quad \rho_{p(\cdot)}(u) < 1 \quad (= 1; > 1) \quad (2.3)$$

$$\|u\|_{L^{p(\cdot)}(\Omega)} > 1 \quad \Rightarrow \quad \|u\|_{L^{p(\cdot)}(\Omega)}^{p^-} \leq \rho_{p(\cdot)}(u) \leq \|u\|_{L^{p(\cdot)}(\Omega)}^{p^+} \quad (2.4)$$

$$\|u\|_{L^{p(\cdot)}(\Omega)} < 1 \quad \Rightarrow \quad \|u\|_{L^{p(\cdot)}(\Omega)}^{p^+} \leq \rho_{p(\cdot)}(u) \leq \|u\|_{L^{p(\cdot)}(\Omega)}^{p^-}. \quad (2.5)$$

Remark 2.1. *If we consider the application $\tilde{\rho}_{p(\cdot)} : L^{p(\cdot)}(\partial\Omega) \rightarrow \mathbb{R}$, $\tilde{\rho}_{p(\cdot)}(u) = \int_{\partial\Omega} |u(x)|^{p(x)} dS$, the corresponding properties (2.3) - (2.5) remain valid.*

Let us introduce now the definition of the isotropic Sobolev space with variable exponent, $W^{1,p(\cdot)}(\Omega)$. We set

$$W^{1,p(\cdot)}(\Omega) = \left\{ u \in L^{p(\cdot)}(\Omega) : |\nabla u| \in L^{p(\cdot)}(\Omega) \right\}$$

endowed with the norm

$$\|u\| = \|u\|_{L^{p(\cdot)}(\Omega)} + \|\nabla u\|_{L^{p(\cdot)}(\Omega)}, \quad (2.6)$$

where by $\|\nabla u\|_{L^{p(\cdot)}(\Omega)}$ we understand $\| |\nabla u| \|_{L^{p(\cdot)}(\Omega)}$. The space $(W^{1,p(\cdot)}(\Omega), \|\cdot\|)$ is a separable and reflexive Banach space (see [10, Theorem 1.3]) and the next proposition is very helpful in handling its norm.

Proposition 2.1. ([8, Proposition 2.3]) *If $u \in W^{1,p(\cdot)}(\Omega)$ then*

$$\|u\| > 1 \quad \Rightarrow \quad \|u\|^{p^-} \leq \int_{\Omega} \left[|\nabla u|^{p(x)} + |u|^{p(x)} \right] dx \leq \|u\|^{p^+};$$

$$\|u\| < 1 \quad \Rightarrow \quad \|u\|^{p^+} \leq \int_{\Omega} \left[|\nabla u|^{p(x)} + |u|^{p(x)} \right] dx \leq \|u\|^{p^-}.$$

We also have two embedding results.

Theorem 2.2. ([7, Proposition 2.4]) *Let $\Omega \subset \mathbb{R}^N$, $N \geq 2$ be a bounded domain with smooth boundary. If $p, q \in C(\overline{\Omega})$ satisfy the condition*

$$1 \leq q(x) < p^*(x), \quad \forall x \in \overline{\Omega},$$

then there is a compact embedding $W^{1,p(\cdot)}(\Omega) \hookrightarrow L^{q(\cdot)}(\Omega)$.

Theorem 2.3. ([6, Corollary 2.4]) *Let $\Omega \subset \mathbb{R}^N$, $N \geq 2$, be a bounded open set with smooth boundary. Suppose that $p \in C_+(\overline{\Omega})$ and $r \in C(\overline{\Omega})$ satisfy the condition*

$$1 \leq r(x) < p^\partial(x), \quad \forall x \in \partial\Omega.$$

Then there is a compact boundary trace embedding $W^{1,p(\cdot)}(\Omega) \hookrightarrow L^{r(\cdot)}(\partial\Omega)$.

We refer to [6] for more details regarding the extension of the classical trace to Lebesgue-Sobolev spaces with variable exponent. Everywhere below, when we refer to the trace of u we will write u instead of $u|_{\partial\Omega}$ or γu .

3 Main Results

In what follows, in addition to hypotheses (A1) - (A4) we assume that function $b : \Omega \rightarrow \mathbb{R}$ satisfies:

(B) $b \in L^\infty(\Omega)$ and there exists $b_0 > 0$ such that $b(x) \geq b_0$ for all $x \in \Omega$.

Also, we suppose that f, g are Carathéodory functions verifying the conditions:

(F) For $q \in C_+(\overline{\Omega})$ with $q^+ < p^-$, there exist $c_1, c_2 > 0$ such that

$$|f(x, t)| \leq c_1 + c_2 |t|^{q(x)-1}$$

for all $x \in \Omega$ and all $t \in \mathbb{R}$;

(G) For $r \in C_+(\overline{\Omega})$ with $r^+ < p^-$, there exist $c_3, c_4 > 0$ such that

$$|g(x, t)| \leq c_3 + c_4 |t|^{r(x)-1}$$

for all $x \in \partial\Omega$ and all $t \in \mathbb{R}$.

Since we deal with the existence and uniqueness of weak solutions for our problem, we introduce the following definition.

Definition 3.1. A function $u \in W^{1,p(\cdot)}(\Omega)$ which verifies

$$\int_{\Omega} a(x, \nabla u) \cdot \nabla v \, dx + \int_{\Omega} b(x) |u|^{p(x)-2} uv \, dx - \int_{\Omega} f(x, u) v \, dx - \int_{\partial\Omega} g(x, u) v \, dS = 0$$

for all $v \in W^{1,p(\cdot)}(\Omega)$ is called a weak solution of (1.1).

We associate to problem (1.1) the energetic functional $I : W^{1,p(\cdot)}(\Omega) \rightarrow \mathbb{R}$ defined by

$$I(u) = \int_{\Omega} A(x, \nabla u) \, dx + \int_{\Omega} \frac{b(x)}{p(x)} |u|^{p(x)} \, dx - \int_{\Omega} F(x, u) \, dx - \int_{\partial\Omega} G(x, u) \, dS,$$

where $F : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$, $G : \partial\Omega \times \mathbb{R} \rightarrow \mathbb{R}$ are given by

$$F(x, s) = \int_0^s f(x, t) dt, \quad G(x, s) = \int_0^s g(x, t) dt.$$

We also define the functional $\Lambda : W^{1,p(\cdot)}(\Omega) \rightarrow \mathbb{R}$ introduced by

$$\Lambda(u) = \int_{\Omega} A(x, \nabla u) \, dx.$$

Proposition 3.1. ([13, Lemma 1]) (i) The functional Λ is well-defined on $W^{1,p(\cdot)}(\Omega)$.
(ii) The functional Λ is of class $C^1(W^{1,p(\cdot)}(\Omega), \mathbb{R})$ and

$$\langle \Lambda'(u), v \rangle = \int_{\Omega} a(x, \nabla u) \cdot \nabla v \, dx,$$

for all $u, v \in W^{1,p(\cdot)}(\Omega)$.

We must mention that the study from [13] is conducted for a $\Lambda_0 : W_0^{1,p(\cdot)}(\Omega) \rightarrow \mathbb{R}$, where $W_0^{1,p(\cdot)}(\Omega)$ represents the Sobolev space with zero boundary values defined as the closure of $C_0^\infty(\Omega)$ with respect to the norm $\|\cdot\|_{W_0^{1,p(\cdot)}(\Omega)} = \|\nabla u\|_{L^{p(\cdot)}(\Omega)}$. However, since

the calculus is almost identical, we omit it for brevity. Using Proposition 3.1, a standard calculus shows that I is well defined and $I \in C^1(W^{1,p(\cdot)}(\Omega); \mathbb{R})$ with

$$\langle I'(u), v \rangle = \int_{\Omega} a(x, \nabla u) \cdot \nabla v \, dx + \int_{\Omega} b(x) |u|^{p(x)-2} uv \, dx - \int_{\Omega} f(x, u) v \, dx - \int_{\partial\Omega} g(x, u) v \, dS$$

for all $u, v \in W^{1,p(\cdot)}(\Omega)$. Thus any critical point $u \in W^{1,p(\cdot)}(\Omega)$ of I is a weak solution to problem (1.1) and we rely our argumentation on the critical point theory. The main tool to establish our existence result is the following theorem.

Theorem 3.1. ([14, 1.2 Theorem]) *Suppose X is a reflexive Banach space of norm $\|\cdot\|_X$ and let $I : X \rightarrow \mathbb{R} \cup \{\infty\}$ be a function such that:*

- (i) *I is coercive on X , i.e., $I(u) \rightarrow \infty$ as $\|u\|_X \rightarrow \infty$.*
- (ii) *I is (sequentially) weakly lower semicontinuous on X , i.e., for any $u \in X$ and any subsequence $(u_n)_n \subset X$ such that $u_n \rightharpoonup u$ weakly in X there holds*

$$I(u) \leq \liminf_{n \rightarrow \infty} I(u_n).$$

Then I is bounded from below on X and attains its infimum in X .

Using the above theorem, we can prove our first main result.

Theorem 3.2. *Let $\Omega \subset \mathbb{R}^N$, $N \geq 2$, be a bounded domain with smooth boundary. Assume that $f : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$, $g : \partial\Omega \times \mathbb{R} \rightarrow \mathbb{R}$ and $a : \Omega \times \mathbb{R}^N \rightarrow \mathbb{R}^N$ are Carathéodory functions and that $a = a(x, \eta)$ is the continuous derivative with respect to η of a function $A : \Omega \times \mathbb{R}^N \rightarrow \mathbb{R}$, $A = A(x, \eta)$. If conditions (A1) - (A4), (B), (F) and (G) are fulfilled, then there exists a weak solution to problem (1.1).*

Proof.

We start by showing that I is coercive. By integrating in the relations provided by (F) and (G), we arrive at

$$|F(x, t)| \leq c_1 |t| + c_2 \frac{|t|^{q(x)}}{q(x)} \quad \text{for all } x \in \Omega \text{ and } t \in \mathbb{R},$$

$$|G(x, t)| \leq c_3 |t| + c_4 \frac{|t|^{r(x)}}{r(x)} \quad \text{for all } x \in \partial\Omega \text{ and } t \in \mathbb{R}.$$

Then, due to relations (2.3) – (2.5) and Remark 2.1,

$$\begin{aligned} \int_{\Omega} F(x, u) \, dx &\leq c_1 \|u\|_{L^1(\Omega)} + \frac{c_2}{q^+} \left(\|u\|_{L^{q(\cdot)}(\Omega)}^{q^+} + \|u\|_{L^{q(\cdot)}(\Omega)}^{q^-} \right), \\ \int_{\partial\Omega} G(x, u) \, dS &\leq c_3 \|u\|_{L^1(\partial\Omega)} + \frac{c_4}{r^+} \left(\|u\|_{L^{r(\cdot)}(\partial\Omega)}^{r^+} + \|u\|_{L^{r(\cdot)}(\partial\Omega)}^{r^-} \right). \end{aligned}$$

Taking into account Theorems 2.2 and 2.3, we obtain that, for $u \in W^{1,p(\cdot)}(\Omega)$ with $\|u\| \geq 1$, there exist $k_1, k_2, k_3, k_4 > 0$ such that

$$\int_{\Omega} F(x, u) dx \leq k_1 \|u\| + k_2 \|u\|^{q^+}, \quad (3.7)$$

$$\int_{\partial\Omega} G(x, u) dS \leq k_3 \|u\| + k_4 \|u\|^{r^+}. \quad (3.8)$$

On the other hand, by (A4) and (B),

$$\int_{\Omega} A(x, \nabla u) dx + \int_{\Omega} \frac{b(x)}{p(x)} |u|^{p(x)} dx \geq \frac{\min\{1, b_0\}}{p^+} \int_{\Omega} [|\nabla u|^{p(x)} + |u|^{p(x)}] dx.$$

Using Proposition 2.1 in the above inequality, we infer that, for $\|u\| \geq 1$,

$$\int_{\Omega} A(x, \nabla u) dx + \int_{\Omega} \frac{b(x)}{p(x)} |u|^{p(x)} dx \geq \frac{\min\{1, b_0\}}{p^+} \|u\|^{p^-}. \quad (3.9)$$

Putting together (3.7), (3.8) and (3.9), we find out that, for $\|u\| \geq 1$,

$$I(u) \geq \frac{\min\{1, b_0\}}{p^+} \|u\|^{p^-} - k_2 \|u\|^{q^+} - k_4 \|u\|^{r^+} - (k_1 + k_3) \|u\|.$$

By considering the hypotheses on p, q and r , we get that $I(u) \rightarrow \infty$ when $\|u\| \rightarrow \infty$, hence I is coercive.

Next, we make the notations

$$\mathcal{F}(u) = \int_{\Omega} F(x, u) dx, \quad \mathcal{G}(u) = \int_{\partial\Omega} G(x, u) dS,$$

and we notice that \mathcal{F}' and \mathcal{G}' are completely continuous, therefore \mathcal{F} and \mathcal{G} are weakly continuous. Following the ideas from [4] and [13] we deduce that I is weakly lower semi-continuous. We are now in position to apply Theorem 3.1. Thus we conclude that problem (1.1) admits at least one weak solution. \square

In order to get the uniqueness of the solution, we introduce new assumptions on f and g :

(F0) f is fulfilling the monotonicity condition

$$(f(x, s) - f(x, t))(s - t) < 0,$$

for all $x \in \Omega$ and $s, t \in \mathbb{R}$ with $s \neq t$;

(G0) g is fulfilling the monotonicity condition

$$(g(x, s) - g(x, t))(s - t) < 0,$$

for all $x \in \partial\Omega$ and $s, t \in \mathbb{R}$ with $s \neq t$.

Now we can formulate our second result.

Theorem 3.3. *Let $\Omega \subset \mathbb{R}^N$, $N \geq 2$, be a bounded domain with smooth boundary. Assume that $f : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$, $g : \partial\Omega \times \mathbb{R} \rightarrow \mathbb{R}$ and $a : \Omega \times \mathbb{R}^N \rightarrow \mathbb{R}^N$ are Carathéodory functions and that $a = a(x, \eta)$ is the continuous derivative with respect to η of a function $A : \Omega \times \mathbb{R}^N \rightarrow \mathbb{R}$, $A = A(x, \eta)$. If conditions (A1) - (A4), (B), (F), (F0), (G) and (G0) are fulfilled, then problem (1.1) admits a unique weak solution.*

Proof.

The existence of solutions is guaranteed by Theorem 3.2. Hence we can assume that there exist two weak solutions to problem (1.1), that is, u_1 and u_2 . First, we replace the solution u by u_1 in Definition 3.1 and we take $v = u_1 - u_2$. We obtain

$$\begin{aligned} & \int_{\Omega} a(x, \nabla u_1) \cdot \nabla(u_1 - u_2) dx + \int_{\Omega} b(x) |u_1|^{p(x)-2} u_1 (u_1 - u_2) dx \\ & - \int_{\Omega} f(x, u_1) (u_1 - u_2) dx - \int_{\partial\Omega} g(x, u_1) (u_1 - u_2) dS = 0. \end{aligned}$$

Then, we replace the solution u by u_2 in Definition 3.1 and we take $v = u_2 - u_1$. We get

$$\begin{aligned} & \int_{\Omega} a(x, \nabla u_2) \cdot \nabla(u_2 - u_1) dx + \int_{\Omega} b(x) |u_2|^{p(x)-2} u_2 (u_2 - u_1) dx \\ & - \int_{\Omega} f(x, u_2) (u_2 - u_1) dx - \int_{\partial\Omega} g(x, u_2) (u_2 - u_1) dS = 0. \end{aligned}$$

By the two previous relations we deduce that

$$\begin{aligned} & \int_{\Omega} [a(x, \nabla u_1) - a(x, \nabla u_2)] \cdot (\nabla u_1 - \nabla u_2) dx + \int_{\Omega} b(x) \left[|u_1|^{p(x)-2} u_1 - |u_2|^{p(x)-2} u_2 \right] (u_1 - u_2) dx \\ & - \int_{\Omega} [f(x, u_1) - f(x, u_2)] (u_1 - u_2) dx - \int_{\partial\Omega} [g(x, u_1) - g(x, u_2)] (u_1 - u_2) dS = 0. \end{aligned}$$

Using (A3), (F0) and (G0), all the terms in the above equality are positive unless $u_1 = u_2$, therefore we have obtained the uniqueness of the weak solution to problem (1.1). \square

4 Comments and connections

A first remark is that, by adding new assumptions to (A1) - (A4), (B), (F) and (G), we can establish a multiplicity result. Moreover, this multiplicity result can be achieved by relaxing the initial conditions (F) and (G) by not imposing a particular order between p and q , respectively between p and r . To be more precise, we refer to the following set of hypotheses:

(A5) The mapping A is even with respect to its second variable, that is,

$$A(x, -\eta) = A(x, \eta)$$

for all $x \in \Omega$ and all $\eta \in \mathbb{R}^N$;

(F1) For $q \in C_+(\overline{\Omega})$ with $q(x) < p^*(x)$ for all $x \in \overline{\Omega}$, there exists $\tilde{c}_1 > 0$ such that

$$|f(x, t)| \leq \tilde{c}_1 |t|^{q(x)-1}$$

for all $x \in \Omega$ and all $t \in \mathbb{R}$;

(F2) There exists $\alpha_1 > p^+$ such that

$$0 < \alpha_1 F(x, t) \leq t f(x, t)$$

for all $x \in \Omega$ and all $t \in \mathbb{R}$;

(F3) The function f is odd with respect to its second variable, that is,

$$f(x, -t) = -f(x, t)$$

for all $x \in \Omega$ and all $t \in \mathbb{R}$;

(G1) For $r \in C_+(\overline{\Omega})$ with $r(x) < p^\partial(x)$ for all $x \in \partial\Omega$, there exists $\tilde{c}_2 > 0$ such that

$$|g(x, t)| \leq \tilde{c}_2 |t|^{r(x)-1}$$

for all $x \in \partial\Omega$ and all $t \in \mathbb{R}$;

(G2) There exists $\alpha_2 > p^+$ such that

$$0 < \alpha_2 G(x, t) \leq t g(x, t)$$

for all $x \in \partial\Omega$ and all $t \in \mathbb{R}$;

(G3) The function g is odd with respect to its second variable, that is,

$$g(x, -t) = -g(x, t)$$

for all $x \in \partial\Omega$ and all $t \in \mathbb{R}$.

By working under conditions (A1) - (A5), (B), (F1) - (F3) and (G1) - (G3), the existence of a sequence of weak solutions to problem (1.1) is obtained in [2] with the aid of the fountain theorem.

Next, to make some other useful connections, we introduce the vectorial function

$$\vec{p} : \overline{\Omega} \rightarrow \mathbb{R}^N, \quad \vec{p}(\cdot) = (p_1(\cdot), \dots, p_N(\cdot)),$$

where $p_i \in C_+(\overline{\Omega})$ for all $i \in \{1, \dots, N\}$. Also, we denote

$$p_M(x) = \max\{p_1(x), \dots, p_N(x)\}$$

and we recall the definition of the anisotropic variable exponent Sobolev space,

$$\begin{aligned} W^{1, \vec{p}(\cdot)}(\Omega) &= \left\{ u \in L^{p_M(\cdot)}(\Omega) : \partial_{x_i} u \in L^{p_i(\cdot)}(\Omega) \text{ for all } i \in \{1, \dots, N\} \right\} \\ &= \left\{ u \in L^1_{loc}(\Omega) : u \in L^{p_i(\cdot)}(\Omega), \partial_{x_i} u \in L^{p_i(\cdot)}(\Omega) \text{ for all } i \in \{1, \dots, N\} \right\}. \end{aligned}$$

The space $W^{1, \vec{p}(\cdot)}(\Omega)$ endowed with the norm

$$\|u\|_{W^{1, \vec{p}(\cdot)}(\Omega)} = \|u\|_{L^{p_M(\cdot)}(\Omega)} + \sum_{i=1}^N \|\partial_{x_i} u\|_{L^{p_i(\cdot)}(\Omega)}$$

is a reflexive Banach space (see [5, Theorem 2.1, Theorem 2.2]). Notice that for $p_1 = p_2 = \dots = p_N = p$, we arrive at the isotropic Sobolev space with variable exponent $W^{1, p(\cdot)}(\Omega)$. Moreover, the norm becomes

$$\|u\|_{W^{1, p(\cdot)}(\Omega)} = \|u\|_{L^{p(\cdot)}(\Omega)} + \sum_{i=1}^N \|\partial_{x_i} u\|_{L^{p(\cdot)}(\Omega)},$$

which is a norm equivalent to $\|\cdot\|$ given by (2.6). Thus, the space $W^{1, p(\cdot)}(\Omega)$ can be viewed as a particular case of $W^{1, \vec{p}(\cdot)}(\Omega)$. However, this is not quite the case for the $p(\cdot)$ -Laplace operator (1.2) and the $\vec{p}(\cdot)$ -Laplace operator defined as

$$\Delta_{\vec{p}(x)}(u) = \sum_{i=1}^N \partial_{x_i} \left(|\partial_{x_i} u|^{p_i(x)-2} \partial_{x_i} u \right). \quad (4.10)$$

Indeed, when we take $p_1 = p_2 = \dots = p_N = p$ in (4.10), we do not get exactly the operator introduced by (1.2). For similar reasons, we can not consider problem (1.1) to be a particular case of the problem studied in [3] in the framework of anisotropic variable exponent spaces,

$$\begin{cases} - \sum_{i=1}^N \partial_{x_i} a_i(x, \partial_{x_i} u) + b(x) |u|^{p_M(x)-2} u = f(x, u) & \text{in } \Omega, \\ u \geq 0 & \text{in } \Omega, \\ \sum_{i=1}^N a_i(x, \partial_{x_i} u) \nu_i = g(x, u) & \text{on } \partial\Omega, \end{cases} \quad (4.11)$$

where $\Omega \subset \mathbb{R}^N$ is a bounded open set with smooth boundary, ν_i , $i \in \{1, \dots, N\}$, are the components of the outer normal unit vector, b satisfies (B) and the applications $a_i : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ are Carathéodory functions fulfilling the following hypotheses for all $i \in \{1, \dots, N\}$:

($\tilde{A}1$) There exists a positive constant \bar{c}_i such that a_i satisfies the growth condition

$$|a_i(x, s)| \leq \bar{c}_i (d_i(x) + |s|^{p_i(x)-1}),$$

for all $x \in \Omega$ and $s \in \mathbb{R}$, where $d_i \in L^{p'_i(\cdot)}(\Omega)$ (with $1/p_i(x) + 1/p'_i(x) = 1$), is a nonnegative function;

($\tilde{A}2$) If we denote by $A_i : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$,

$$A_i(x, s) = \int_0^s a_i(x, t) dt,$$

then the following inequalities hold:

$$|s|^{p_i(x)} \leq a_i(x, s)s \leq p_i(x) A_i(x, s),$$

for all $x \in \Omega$ and $s \in \mathbb{R}$;

($\tilde{A}3$) a_i is fulfilling

$$(a_i(x, s) - a_i(x, t))(s - t) > 0,$$

for all $x \in \Omega$ and $s, t \in \mathbb{R}$ with $s \neq t$.

Also, in addition to (F0) and (G0), the Carathéodory functions $f : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ and $g : \partial\Omega \times \mathbb{R} \rightarrow \mathbb{R}$ are fulfilling conditions very much alike to conditions (F) and (G):

(\tilde{F}) There exist a positive constant k_1 and $q \in L_+^\infty(\Omega)$ with $q^+ < p_m^-$, such that

$$|f(x, s)| \leq k_1 \left(1 + |s|^{q(x)-1} \right),$$

for all $x \in \Omega$ and $s \in \mathbb{R}$, where

$$p_m(x) = \min\{p_1(x), \dots, p_N(x)\};$$

(\tilde{G}) There exist a positive constant k_2 and $r \in C(\bar{\Omega})$ with $r^+ < p_m^-$ such that

$$|g(x, s)| \leq k_2 \left(1 + |s|^{r(x)-1} \right),$$

for all $x \in \partial\Omega$ and $s \in \mathbb{R}$.

Although problem (1.1) is not a particular case of (4.11), it is clear that the two problems are closely related and in many aspects (4.11) is a generalization of (1.1). Furthermore, as showed in [3], under the previous conditions, an existence and uniqueness result can be provided using the same main argument, that is, Theorem 3.1. Therefore a natural question arises: could we obtain a sequence of weak solutions to (4.11) by applying the same strategy as in [2]? At least for the time being, we can not give a positive answer to this question. A major impediment is that we do not know if the functional $J : W^{1, \vec{p}(\cdot)}(\Omega) \rightarrow \mathbb{R}$, $J(u) = \int_\Omega \sum_{i=1}^N A_i(x, \partial_{x_i} u) dx$ is of type (S+). We remind that J is said to be of type (S+) if any sequence $(u_n)_n \subset W^{1, \vec{p}(\cdot)}(\Omega)$ that is weakly convergent to $u \in W^{1, \vec{p}(\cdot)}(\Omega)$ such that

$$\limsup_{n \rightarrow \infty} \langle J'(u_n), u_n - u \rangle \leq 0$$

converges strongly to u in $W^{1, \vec{p}(\cdot)}(\Omega)$. The arguments used to show that J is of type (S+) when is defined on $W_0^{1, \vec{p}(\cdot)}(\Omega)$ (see [1, Lemma 2]) fail when we replace this space with $W^{1, \vec{p}(\cdot)}(\Omega)$. For more details we send the reader to [3, Section 4], where is also debated the applicability of the mountain pass theorem and of the Ekeland principle to problem (4.11).

Acknowledgment. The author was supported by a grant of the Romanian National Authority for Scientific Research, CNCS - UEFISCDI, project number PN-II-RU-TE-2011-3-0223.

References

- [1] Boureanu, M.-M., *Infinitely many solutions for a class of degenerate anisotropic elliptic problems with variable exponent*, Taiwanese Journal of Mathematics **15** (2011), 2291–2310.
- [2] Boureanu, M.-M. and Preda, F., *Infinitely many solutions for elliptic problems with variable exponent and nonlinear boundary conditions*, Nonl. Diff. Eq. and Appl. (NoDEA) **19** (2012), 235–251.
- [3] Boureanu, M.-M. and Rădulescu, V., *Anisotropic Neumann problems in Sobolev spaces with variable exponent*, Nonlinear Anal. TMA, **75** (2012), 4471–4482.
- [4] Boureanu, M.-M. and Udrea, D.N., *Existence and multiplicity results for elliptic problems with $p(\cdot)$ - growth conditions*, manuscript.
- [5] Fan, X., *Anisotropic variable exponent Sobolev spaces and $\vec{p}(\cdot)$ -Laplacian equations*, Complex Variables and Elliptic Equations **55** (2010), 1–20.
- [6] Fan, X., *Boundary trace embedding theorems for variable exponent Sobolev spaces*, J. Math. Anal. Appl. **339** (2008), 1395–1412.
- [7] Fan, X., *Solutions for $p(x)$ -Laplacian Dirichlet problems with singular coefficients*, J. Math. Anal. Appl. **312** (2005), 464–477.
- [8] Fan, X. and Han, X., *Existence and multiplicity of solutions for $p(x)$ -Laplacian equations in \mathbb{R}^N* , Nonlinear Anal. **59** (2004), 173–188.
- [9] Fan, X. and Zhao, D., *On the spaces $L^{p(x)}(\Omega)$ and $W^{m,p(x)}(\Omega)$* , J. Math. Anal. Appl. **263** (2001), 424–446.
- [10] Kováčik, O. and Rákosník, J., *On spaces $L^{p(x)}$ and $W^{k,p(x)}$* , Czechoslovak Math. J. **41** (1991), 592–618.
- [11] Kristály, A., Lisei, H. and Varga, C., *Multiple solutions for p -Laplacian type equations*, Nonlinear Anal. TMA **68** (2008), 1375–1381.
- [12] Le, V.K., *On a sub-supersolution method for variational inequalities with Leray-Lions operators in variable exponent spaces*, Nonlinear Anal. **71** (2009), 3305–3321.
- [13] Mihăilescu, M. and Rădulescu, V., *A multiplicity result for a nonlinear degenerate problem arising in the theory of electrorheological fluids*, Proc. Roy. Soc. London Ser. A **462** (2006), 2625–2641.
- [14] Struwe, M., *Variational Methods: Applications to Nonlinear Partial Differential Equations and Hamiltonian Systems*, Springer, Heidelberg, 1996.