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#### ON GENERALIZED WEAKLY SYMMETRIC MANIFOLDS

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#### Abstract

The purpose of the study is to introduce a new type of space, called generalized weakly symmetric space. The existence of such space is ensured by a non-trivial example.

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### 1 Introduction

The notion of weakly symmetric Riemannian manifold has been introduced by Tamássy and Binh [25]. Thereafter, a lot of research has been carried out in this topic. For details, we refer to [10], [13], [14], [16], [19], [20], [21], [22], [24] and the references there in. In the spirit of Tamássy and Binh [25], a non-flat *n*dimensional Riemannian manifold  $(M^n, g)(n > 2)$ , is said to be weakly symmetric manifold, if its curvature tensor  $\overline{R}$  of type (0, 4) is not identically zero and satisfies the relation

$$(\nabla_X \bar{R})(Y, U, V, W) = A(X)\bar{R}(Y, U, V, W) + B(Y)\bar{R}(X, U, V, W) + B(U)\bar{R}(Y, X, V, W) + D(V)\bar{R}(Y, U, X, W) + D(W)\bar{R}(Y, U, V, X)$$
(1)

where A, B, & D are non-zero 1-forms defined by  $A(X) = g(X, \theta_1), B(X) = g(X, \varrho_1)$  and  $D(X) = g(X, \phi_1)$  for all X and  $\overline{R}(Y, U, V, W) = g(R(Y, U)V, W),$  $\nabla$  being the operator of the covariant differentiation with respect to the metric tensor g. An n-dimensional manifold of this kind is denoted by  $(WS)_n$ .

Keeping in tune with Dubey [12], we introduce a new type of space called generalized weakly symmetric manifold which is abbreviated by  $(GWS)_n$ -space and defined as follows

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A non-flat *n*-dimensional Riemannian manifold  $(M^n; g)$  (n > 2), is termed as generalized weakly symmetric manifold, if its Riemannian curvature tensor  $\bar{R}$  of type (0; 4) is not identically zero and admits the identity

$$(\nabla_X \bar{R})(Y, U, V, W) = A(X)\bar{R}(Y, U, V, W) + B(Y)\bar{R}(X, U, V, W) + B(U)X\bar{R}(Y, X, V, W) + D(V)\bar{R}(Y, U, X, W) + D(W)\bar{R}(Y, U, V, X) + \alpha(X)G(Y, U, V, W) + \beta(Y)G(X, U, V, W) + \beta(U) G(Y, X, V, W) + \gamma(V) G(Y, U, X, W) + \gamma(W) G(Y, U, V, X)$$
(2)

where

$$G(Y, U, V, W) = [g(U, V)g(Y, W) - g(Y, V)g(U, W)]$$
(3)

and A, B, D,  $\alpha$ ,  $\beta$  &  $\gamma$  are non-zero 1-forms which are defined as  $A(X) = g(X, \theta_1), B(X) = g(X, \phi_1), D(X) = g(X, \pi_1), \alpha(X) = g(X, \theta_2), \beta(X) = g(X, \phi_2)$ and  $\gamma(X) = g(X, \pi_2)$ . The local expression of (2) is

$$R_{mnpq,k} = A_k \bar{R}_{mnpq} + B_m \bar{R}_{knpq} + B_n \bar{R}_{mkpq} + D_p \bar{R}_{mnkq} + D_q \bar{R}_{mnpk} + \alpha_k G_{mnpq} + \beta_m G_{knpq} + \beta_n G_{mkpq} + \gamma_p G_{mnkq} + \gamma_q G_{mnpk}, \quad (4)$$

where  $A_i$ ,  $B_i$ ,  $D_i$ ,  $\alpha_i$ ,  $\beta_i$  and  $\gamma_i$  are non-zero co-vectors. The beauty of such  $(GWS)_n$ -space is that it has the flavour of

(i) symmetric space[6] (for  $A = B = D = \alpha = \beta = \gamma = 0$ ),

(ii) recurrent space[29] (for  $A \neq 0$  and  $B = D = \alpha = \beta = \gamma = 0$ ),

(iii) generalized recurrent space [12] (for  $A \neq 0, \alpha \neq 0, B = D = \beta = \gamma = 0$ ),

(iv) pseudo symmetric space[7] (for  $\frac{A}{2} = B = D = \delta \neq 0, \alpha = \beta = \gamma = 0$ ),

(v) generalized pseudo symmetric space[1] (for  $\frac{A}{2} = B = D = \delta \neq 0 \& \frac{\alpha}{2} = \beta = \gamma = \mu \neq 0$ ),

(vi) semi-pseudo symmetric space[27] (for  $B = D = \delta \neq 0$ ,  $A = \alpha = \beta = \gamma = 0$ ),

(vii) generalized semi-pseudo symmetric space[2] (for  $A = 0 = \alpha, B = D = \delta \neq 0 \& \beta = \gamma = \mu \neq 0$ ),

(viii) almost pseudo symmetric space[8] (for A = E + H, B = D = H &  $\alpha = \beta = \gamma = 0$ ),

(ix) almost generalized pseudo symmetric space([3], [4], [5]) (for A = E + H, B = D = H &  $\alpha = \lambda + \psi, \beta = \gamma = \lambda$ ) and

(x) weakly symmetric space [25](for  $A, B, D \neq 0$  &  $\alpha = \beta = \gamma = 0$ ).

We organized this paper as follows; Section 2 is concerned with some results on  $(GWS)_n$ -manifold. Among other things, it is pointed out that a weakly concirculally symmetric space can always be considered as a generalized weakly symmetric space. In section 3, the existence of a generalized weakly symmetric space is ensured by a non-trivial example.

## **2** Some results on $(GWS)_n$ -manifold

In this section, we consider a Riemann manifold  $(M^n, g)$  n > 2 which is generalized weakly symmetric. Now, contracting (4) we find

$$(\nabla_X S)(Y, W) = A(X)S(Y, W) + B(Y)S(X, W) + D(W)S(Y, X)$$
(5)  
$$-B(R((Y, X)W) + D(R(X, W)Y) + (n-1)[\alpha(X)$$
  
$$g(Y, W) + \beta(Y)g(X, W) + \gamma(W)g(Y, X)]$$
  
$$-\beta(Y) g(X, W) + [\beta(X) + \gamma(X)] g(Y, W) - \gamma(W)g(X, Y)$$

which yields after further contraction

$$dr(X) = A(X) r + 2B_1(X) + 2 D_1(X) + (n-1)[n\alpha(X) + 2\beta(X) + 2\gamma(X)]$$
(6)

where  $\bar{A}_1(X) = S(X, \theta_1)$ .

Next, if we suppose that the scalar curvature of a  $(GWS)_n$ -space is non-zero constant, then (6) becomes

$$[A(X) r + 2B_1(X) + 2 D_1(X) = -(n-1)[n\alpha(X) + 2\beta(X) + 2\gamma(X)].$$
(7)

This leads to the following:

**Theorem 1.** The 1-forms of a  $(GWS)_n$ -manifold are related by the expression (7) provided that the scalar curvature is non-zero constant.

**Definition 1.** [1] A non-flat n-dimensional Riemannian manifold  $(M^n, g)$  (n > 2), is said to be a generalized weakly Ricci-symmetric manifold (which is abbreviated by  $(GWRS)_n$ -space), if its Ricci tensor S of type (0, 2) is not identically zero and admits the identity

$$(\nabla_X S)(Y, W) = A(X)S(Y, W) + B(Y)S(X, W) + \overline{D}(W)S(Y, X) + \overline{\alpha}(X)(Y, W) + \overline{\beta}(Y)g(X, W) + \overline{\gamma}(W) g(Y, X)$$
(8)

where  $\bar{A}$ ,  $\bar{B}$ ,  $\bar{D}$ ,  $\bar{\alpha}$ ,  $\bar{\beta} \& \bar{\gamma}$  are non-zero 1-forms which are defined as  $\bar{A}(X) = g(X,\bar{\theta}_1)$ ,  $\bar{B}(X) = g(X,\bar{\phi}_1)$ ,  $\bar{D}(X) = g(X,\bar{\pi}_1)$ ,  $\bar{\alpha}(X) = g(X,\bar{\theta}_2)$ ,  $\bar{\beta}(X) = g(X,\bar{\phi}_2)$ and  $\bar{\gamma}(X) = g(X,\bar{\pi}_2)$ . In particular, if  $\bar{\alpha} = \bar{\beta} = \bar{\gamma} = 0$ , the relation (8) reduces to weakly Ricci symmetric manifold[26].

**Theorem 2.** A  $(GWS)_n$ -manifold is necessarily a  $(GWPRS)_n$ -manifold provided that the relation

$$S(X,\phi_1) + S(X,\pi_1) = -(n-1)[\beta(X) + \gamma(X)]$$
(9)

holds for all X.

*Proof.* It follows directly from (5).

Again, in analogous with the definition of a  $(GWS)_n$ -manifold, a non-flat concircular curvature tensor

$$\bar{E}(Y,U,V, W) = \bar{R}(Y,U,V, W) - \frac{r}{n(n-1)}G(Y,U,V, W),$$
(10)

is called a weakly concirculally symmetric if it satisfies the identity

$$(\nabla_X \bar{E})(Y, U, V, W) = A(X) \ \bar{E}(Y, U, V, W) + B(Y) \bar{E}(X, U, V, W) + B(U) \bar{E}(Y, X, V, W) + D(V) \bar{E}(Y, U, X, W) + D(W) \bar{E}(Y, U, V, X).$$
(11)

We observe that for the following choice of the 1-forms

$$\begin{split} \alpha(X) &= \frac{[dr(X) - rA(X)]}{n(n-1)}, \ \beta(X) = -\frac{r}{n(n-1)}B(X) \\ \& \ \gamma(X) &= -\frac{r}{n(n-1)}D(X) \ \forall \ X. \end{split}$$

the equation (11) turns into (5). This motivates us to state

**Theorem 3.** A weakly concircularly symmetric space is necessarily a  $(GWS)_n$ -space.

However, the converse of the above Theorem may not true. Again, contracting Y over W in (8) we obtain

$$(\nabla_X S)(U,V) - \frac{dr(X)}{n}g(U,V) = A(X)[S(U,V) - \frac{r}{n}g(U,V)] +B(U)[S(X, V) - \frac{r}{n}g(X, V)] -B(E(U,X)V) + D(E(X,V)U) +D(V)[S(U,X) - \frac{r}{n}g(U, X)]$$
(12)

which yields

$$(\nabla_X Z)(Y, V) = A(X)Z(Y, V) + B(Y)Z(X, V) + D(V)Z(Y, X) - B(E(Y, X)V) + D(E(X, V)Y)$$
(13)

where Z stands for a well known Z-tensor ([17], [18]). This leads us to state **Theorem 4.** A weakly concircularly symmetric space is a weakly Z-symmetric space if

$$Z(U,\phi) = Z(U,\pi).$$
(14)

*Proof.* It follows directly from (13).

# 3 Existence of generalized weakly symmetric space

**Example 1.** Let  $(\mathbb{R}^4, g)$  be a 4-dimensional Riemannian space endowed with the Riemann metric g given by

$$ds^{2} = g_{ij}dx^{i}dx^{j} = (x^{4})^{4/3}[(dx^{1})^{2} + (dx^{2})^{2} + (dx^{3})^{2}] - (dx^{4})^{2}, \quad (15)$$

(i, j = 1, 2, 3, 4).

The non-zero components of Riemannian curvature tensor are

$$R_{1212} = \frac{4}{9} (x^4)^{2/3} = R_{1313} = R_{2323},$$
  

$$R_{1414} = R_{2424} = R_{3434} = \frac{2}{9(x^4)^{2/3}},$$

Making use of (15), we can easily bring out

$$G_{1212} = G_{1313} = G_{2323} = -(x^4)^{8/3},$$
  
 $G_{1414} = G_{2424} = G_{3434} = -(x^4)^{4/3}$ 

Covariant derivatives of Riemannian curvature tensors are

$$\begin{aligned} R_{1212,4} &= R_{1313,4} = R_{2323,4} = -\frac{8}{9(x^4)^{1/3}}, \\ R_{1214,2} &= R_{1314,3} = R_{2324,3} = -\frac{4}{9(x^4)^{1/3}}, \\ R_{1224,1} &= R_{1334,1} = R_{2334,2} = \frac{4}{9(x^4)^{1/3}}, \\ R_{1414,4} &= R_{2424,4} = R_{3434,4} = -\frac{4}{9(x^4)^{5/3}}. \end{aligned}$$

For the following choice of the 1-forms

$$A_{i} = \frac{1}{x^{4}}, \text{ for } i = 4$$
  
= 0, otherwise  
$$B_{i} = -\frac{19}{3x^{4}}, \text{ for } i = 4$$
  
= 0, otherwise  
$$D_{i} = -\frac{19}{3x^{4}}, \text{ for } i = 4$$
  
= 0, otherwise  
$$\alpha_{i} = \frac{8}{9(x^{4})^{3}}, \text{ for } i = 4$$
  
= 0, otherwise  
$$\beta_{i} = -\frac{64}{27(x^{4})^{3}}, \text{ for } i = 4$$
  
= 0, otherwise  
$$\gamma_{i} = -\frac{64}{27(x^{4})^{3}}, \text{ for } i = 4$$
  
= 0, otherwise

one can easily fit the followings

where, k = 1, 2, 3, 4. As a consequence of the above one can say that

**Theorem 5.** There exists a  $(\mathbb{R}^4, g)$  which is a generalized weakly symmetric space with non-zero and non-constant scalar curvature for the above mentioned choice of the *i*-forms.

It is clear that the manifold under considered metric can't be symmetric, recurrent, generalized recurrent and almost pseudo symmetric space.

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