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DRAZIN INVERSE: REPRESENTATION, APPROXIMATION, CONTINUITY AND ILLUSTRATIONS

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Abstract

In this paper, we present some characteristics and expressions of the Drazin inverse for matrices and bounded linear operators in Banach spaces. We give a survey of some of results on the continuity of the Moore-Penrose and Drazin inverse, direct technics for computing the Drazin inverse are discussed, they are based on Euler-Knopp Method and characterized in terms of a limiting process. The examples presented are for illustrative purposes, some of which are provided for testing the considered iterative processes.

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1 Introduction and preliminary results

The main theme of this paper is the study of a generalized inverse introduced by M. P. Drazin, and its generalization due to J. J. Koliha. $\mathbb{C}^{m \times n}$ denotes the set of all $m \times n$ matrices, with complex entries, equipped with the Euclidean norm. Suppose that $(A_j)_{j \in \mathbb{N}}$ is a sequence of $m \times n$ matrices, and $A \in \mathbb{C}^{m \times n}$, then $(A_j)_{j \in \mathbb{N}}$ converges to A if and only if the entries of A_j converge to the corresponding entries of A, as $j \to \infty$. Let $A \in \mathbb{C}^{m \times n}$, Penrose has proved in [15] that the system:

$$AXA = A, \ XAX = X, \ (AX)^* = AX, \ (XA)^* = XA$$

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has a unique solution, which he called the Moore-Penrose inverse of A and denoted by $X = A^{\dagger}$. Let us recall that for any $A \in \mathbb{C}^{m \times n}$, we have $(A^{\dagger})^{\dagger} = A$, $(A^*)^{\dagger} = (A^{\dagger})^*$, $(A^*A)^{\dagger} = A^{\dagger}(A^{\dagger})^*$, but in general, $A^{\dagger}A \neq AA^{\dagger}$.

Contrary to the usual inverse of a square matrix, it is well known that the Moore-Penrose inverse of a matrix is not necessarily a continuous function of the elements of the matrix. Indeed, let $A = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ and $B = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$, for each $\varepsilon > 0$, we have $(A + \varepsilon B)^{\dagger} = \begin{pmatrix} 1 & 0 \\ 0 & \varepsilon \end{pmatrix}^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & \varepsilon^{-1} \end{pmatrix}$, hence $(A + \varepsilon B) \to A$, but $(A + \varepsilon B)^{-1}$ has no limit when $\varepsilon \to 0^+$.

The following theorem gives necessary and sufficient conditions for the continuity of the Moore-Penrose inverse of matrix.

Theorem 1. ([15]) Let $A, A_j, j \in \mathbb{N}$, be $m \times n$ complex matrices such that $\lim_{j \to \infty} A_j = A$. Then, $\lim_{j \to \infty} A_j^{\dagger} = A^{\dagger}$ if and only if there exists $q \in \mathbb{N}$ for which $rankA_j = rankA$, for all $j \ge q$.

Let $\mathcal{B}(X)$ be the algebra of all bounded linear operators on a complex Banach space X, $\|.\|$ represents the norm of X. For $A \in \mathcal{B}(X)$, write $\mathcal{N}(A)$, $\mathcal{R}(A)$, $\sigma(A)$, $\rho(A)$ and r(A), as the null space, the range, the spectrum, the resolvent set and the spectral radius of A, respectively. For $\lambda \in \rho(A)$, $(\lambda - A)^{-1}$ is the resolvent operator of A. I denotes the identity operator on X and A^* is the adjoint operator of A. By $\sigma'(A)$ we denote the set of all non-zero elements of $\sigma(A)$. By $iso\sigma(A)$ we define the set of all isolated spectral points of A. If M is a subspace of X, then $A_{|M}$ denotes the restriction of A to M. It is well known (see e.g. [3]) that $A \in \mathcal{B}(X)$ has closed range if and only if there exists a unique operator $A^{\dagger} \in \mathcal{B}(X)$, the Moore-Penrose inverse of A, which satisfies the following properties:

$$AA^{\dagger}A = A, \ A^{\dagger}AA^{\dagger} = A^{\dagger}, \ (AA^{\dagger})^* = AA^{\dagger} \text{ and } (A^{\dagger}A)^* = A^{\dagger}A.$$

In general, if $\lim_{j\to\infty} A_j = A$ uniformly, $(A_j)_{j\in\mathbb{N}}$, $A \in \mathcal{B}(X)$, and each A_j has a closed range, then A need not have a closed range.

Example 1. Let $X = l_2$ the space of square-summable complex sequences. Define $A_j, j \in \mathbb{N}^*$, and A on l_2 by:

$$A_{j}(x_{1}, x_{2}, ..., x_{j}, x_{j+1}, ...) = \left(x_{1}, \frac{x_{2}}{2}, ..., \frac{x_{j}}{j}, 0, 0, ...\right),$$
$$A(x_{1}, x_{2}, ..., x_{j}, x_{j+1}, ...) = \left(x_{1}, \frac{x_{2}}{2}, ..., \frac{x_{j}}{j}, \frac{x_{j+1}}{j+1}, ...\right)$$

Each A_j is of finite rank and thus with closed range and Moore-Penrose invertible operator. It is also clear that the sequence $(A_j)_{j\in\mathbb{N}^*}$ is uniformly convergent to A as $j \to \infty$. But the limit A does not have a closed range in l_2 because A is a compact operator.

The continuity of the Moore-Penrose inverse of an operator on Hilbert spaces has been studied by Izumino [7]. If X is a Hilbert space, let $(A_j)_{j\in\mathbb{N}}$ be a sequence in $\mathcal{B}(X)$, $A \in \mathcal{B}(X)$, and $\lim_{j\to\infty} A_j = A$. If A_j^{\dagger} , for all $j \in \mathbb{N}$, and A^{\dagger} exist, it is shown in [7] that the following four conditions are equivalent:

(1)
$$\lim_{j \to \infty} A_j^{\dagger} = A^{\dagger}.$$
 (2)
$$\sup_{j \in \mathbb{N}} \left\| A_j^{\dagger} \right\| < \infty.$$

(3)
$$\lim_{j \to \infty} A_j^{\dagger} A_j = A^{\dagger} A.$$
 (4)
$$\lim_{j \to \infty} A_j A_j^{\dagger} = A A^{\dagger}.$$

The Drazin inverses of the elements of $\mathbb{C}^{n \times n}$ and $\mathcal{B}(X)$ have been intensively studied by authors such as Ben-Israel and Greville [1] and King [8], one may also refer to [[5], [17]] for some interesting applications about the Drazin inverse in singular differential and difference equations, Markov chain, numerical analysis,

... In this paper, we shall give, by analogy with the Moore-Penrose inverse, representation and computational procedures for the Drazin inverse. Let's recall some well-known results obtained for the Drazin inverse of a square matrix and the Drazin inverse of a bounded linear operator.

Let $A \in \mathbb{C}^{n \times n}$, with k = ind(A) the smallest positive number such that $rankA^{k+1} = rankA^k$, the Drazin inverse of A is defined to be the unique matrix $X \in \mathbb{C}^{n \times n}$ that satisfying the following equations:

$$XAX = X, AX = XA \text{ and } A^{k+1}X = A^k.$$
 (1)

It is denoted by $X = A^D$. In particular, a square matrix always has Drazin inverse and if ind(A) = 0, then A is invertible and $A^D = A^{\dagger} = A^{-1}$. Campbell and Meyer gave in [5] an explicit expression of the Drazin inverse of a square matrix via its canonical form representation.

Theorem 2. Let $A \in \mathbb{C}^{n \times n}$ is such that ind(A) = k > 0, then there exists a non-singular matrix P such that:

$$A = P \begin{pmatrix} C & 0\\ 0 & N \end{pmatrix} P^{-1}$$
(2)

where C is non-singular and N is nilpotent of index k.

Furthermore, if P, C and N are any matrices satisfying the above conditions, then:

$$A^{D} = P \begin{pmatrix} C^{-1} & 0 \\ 0 & 0 \end{pmatrix} P^{-1}.$$
 (3)

Proof. Let $\mathcal{B} = \{e_1, ..., e_r, e_{r+1}, ..., e_n\}$ be a basis for \mathbb{C}^n such that $\{e_1, ..., e_r\}$ is a basis for $\mathcal{R}(A^k)$ and $\{e_{r+1}, ..., e_n\}$ is a basis for $\mathcal{N}(A^k)$, k = ind(A) > 0. $\mathcal{R}(A^k)$ and $\mathcal{N}(A^k)$ are invariant subspaces for A and $A^k(\mathcal{N}(A^k)) = \{0\}$, on the other hand A restricted to $\mathcal{R}(A^k)$, $C = A_{|\mathcal{R}(A^k)}$, is invertible and its restriction to $\mathcal{N}(A^k)$, $N = A_{|\mathcal{N}(A^k)}$, is nilpotent of degree k. So, we obtain the block form for A if $P = [e_1, ..., e_n]$. We can easily verify that the matrix A^D given by (3) satisfies the three equations (1) and then by uniqueness A^D is necessarily the Drazin inverse of A.

A first application of this representation is the following result:

Proposition 1. Let $A \in \mathbb{C}^{n \times n}$, then $AA^{D}A = A$ if and only if $ind(A) \leq 1$.

Proof. If ind(A) = 0, then A is invertible, $A^D = A^{-1}$ and $AA^DA = AA^{-1}A = A$. Suppose that $in(A) \ge 1$. Then by virtue of the canonical form representation (2) of A and the corresponding expression (3) of A^D , we have $AA^DA = A$ if and only if N = 0. But N = 0 is equivalent to ind(A) = 1.

Several methods and efficient algorithms have been given for computation of Moore-Penrose inverse of singular matrices and bounded linear operators with closed range, where this generalized inverse can be represented as the limit of a sequence of matrices or operators, respectively. The principle is to construct an iterative process of computing a sequence that converges to the generalized inverse. In what follows we explain this process for the Drazin inverse of a matrix and for a bounded linear operator and we estimate the corresponding error bounds. We also study the continuity of the generalized Drazin inverse.

The purpose of Section 1 is to present definitions and results that will be used throughout the paper. In Section 2, we recall and discuss some computational procedures for the Drazin inverse of a square matrix. The aim of Section 3 is to investigate the continuity of Drazin inverse in finite-dimensional case. Necessary and sufficient conditions for the continuity of the Drazin inverse of a matrix are given. In Section 4, we present the Drazin inverse (generalized Drazin inverse) of an operator, its uniqueness, existence, and some basic properties. We give also a representation theorem and a computational procedure of the Drazin inverse. In Section 5, we discuss some remarkable properties of the generalized Drazin inverse and we study its continuity in $\mathcal{B}(X)$. The results of each section are described in detail and interpreted by interesting examples.

2 Computational procedure for the Drazin inverse of a matrix

For $A \in \mathbb{C}^{n \times n}$, A^D can be computed recursively by the well known algorithms [6]. We have chosen to explain here the procedure developed by [17] for the computational of Drazin inverse and corresponding error bound. Wei and Wu found in [17] a specific expression and computational procedures for Drazin inverse, they have established the following formula for $A \in \mathbb{C}^{n \times n}$ with real spectrum and ind(A) = k:

$$A^{D} = \lim_{j \to \infty} S_{j}\left(\widetilde{A}\right) A^{l}, \qquad (4)$$

$$\frac{\left\|A^{D} - S_{j}\left(\widetilde{A}\right) A^{l}\right\|_{P}}{\|A^{D}\|_{P}} \leq \max_{x \in \sigma(\widetilde{A})} |S_{j}(x)x - 1| + \mathcal{O}\left(\varepsilon\right), \ \varepsilon > 0,$$

where $(S_j(x))_{j\in\mathbb{N}}$ is a family of continuous real valued functions on an open set Ω such that $\sigma\left(\widetilde{A}\right) \subset \Omega \subset [0,\infty[$, with $\lim_{j\to\infty} S_j(x) = \frac{1}{x}$ uniformly on the spectrum

 $\sigma\left(\widetilde{A}\right)$ of $\widetilde{A} = (A^{l+1})_{|\mathcal{R}(A^k)}$ for $l \ge k$, P is an invertible matrix such that $P^{-1}AP$ is the Jordan canonical form of A and $||A||_P = ||P^{-1}AP||$.

Consider the following sequence with parameter $\alpha > 0$:

$$S_j(x) = \alpha \sum_{m=0}^{j} (1 - \alpha x)^m,$$
 (5)

which can be viewed as the Euler-Knopp transform of the series $\sum_{j=0}^{\infty} (1-x)^j$. Clearly, $\lim_{j\to\infty} S_j(x) = \frac{1}{x}$ uniformly on any compact subset of the set:

$$E_{\alpha} = \{x : |1 - \alpha x| < 1\} = \left\{x : 0 < x < \frac{2}{\alpha}\right\}.$$
 (6)

Lemma 1. If $A \in \mathbb{C}^{n \times n}$ with ind(A) = k, $\widetilde{A} = (A^{l+1})_{|\mathcal{R}(A^k)|}$ for $l \ge k$, and the spectrum of A is real, then $\sigma\left(\widetilde{A}\right) \subset \left[\frac{1}{\|A^D\|^{l+1}}, \|A\|^{l+1}\right]$.

Proof. Let $\{\lambda_1, ..., \lambda_r\}$ be the nonzero eigenvalues of A where $rank(A^k) = r$. Hence, $0 < \lambda_i^{l+1} \in \sigma\left(\widetilde{A}\right) \subseteq \sigma\left(A^{l+1}\right)$, i = 1, ..., r. It is clear that $ind(A^{l+1}) = 1$ and $\frac{1}{\lambda_i^{l+1}} \in \sigma\left(\left(A^D\right)^{l+1}\right)$ and thus $\frac{1}{\lambda_i^{l+1}} \leq \left\|A^D\right\|^{l+1}$, i = 1, ..., r. Therefore, $\lambda \geq \frac{1}{\|A^D\|^{l+1}}$ for every $\lambda \in \sigma\left(\widetilde{A}\right)$. Moreover, since $\|A^{l+1}\| = \left\|\left(A^{l+1}\right)_{|\mathcal{R}(A^k)}\right\|$, we have $\left\|\widetilde{A}\right\| \leq \|A\|^{l+1}$ and then $\lambda \leq \|A\|^{l+1}$ for every $\lambda \in \sigma\left(\widetilde{A}\right)$.

Since, by Lemma 1, $\sigma\left(\widetilde{A}\right) \subset \left]0, \|A\|^{l+1}\right]$, if we choose the parameter α such that $0 < \alpha < \frac{2}{\|A\|^{l+1}}$, and $\left]0, \|A\|^{l+1}\right] \subseteq E_{\alpha}$ then we have the representation:

$$A^{D} = \alpha \sum_{j=0}^{\infty} \left(I - \alpha A^{l+1} \right)^{j} A^{l}.$$
(7)

Let us pose:

$$A_j = \alpha \sum_{m=0}^{j} \left(I - \alpha A^{l+1} \right)^m A^l.$$
(8)

Then $A_0 = \alpha A^l$, $A_{j+1} = (I - \alpha A^{l+1}) A_j + A_0$, $j \in \mathbb{N}$, and by construction $\lim_{j \to \infty} A_j = A^D$. Now, remark that the sequence of functions $(S_j(x))_{j \in \mathbb{N}}$ satisfies:

$$xS_{j+1}(x) - 1 = (1 - \alpha x) (xS_j(x) - 1), \ j \in \mathbb{N},$$
(9)

hence,

$$|xS_{j}(x) - 1| = |1 - \alpha x|^{j+1} \le \left[\max\left(\left| 1 - \alpha \|A\|^{l+1} \right|, \left| 1 - \frac{\alpha}{\|A^{D}\|^{l+1}} \right| \right) \right]^{j+1}$$
(10)

which tends to 0 as $j \to \infty$ if $x \in \sigma(\widetilde{A})$ and $0 < \alpha < \frac{2}{\|A\|^{l+1}}$, and estimates by virtue of (4) the variation of the errors. So, we have shown the following approximation result.

Theorem 3. Let $A \in \mathbb{C}^{n \times n}$ with ind(A) = k, $\widetilde{A} = (A^{l+1})_{|\mathcal{R}(A^k)|}$ for $l \geq k$, and the spectrum of A is real. Then the sequence $(A_j)_{j \in \mathbb{N}}$ defined by (8) converges to the Drazin inverse A^D of A if $0 < \alpha < \frac{2}{\|A\|^{l+1}}$. Furthermore, the error bound is:

$$\frac{\left\|A_{j}-A^{D}\right\|_{P}}{\left\|A^{D}\right\|_{P}} \leq \beta^{j+1} + \mathcal{O}\left(\varepsilon\right), \varepsilon > 0$$

where $\beta = \max\left(\left|1 - \alpha \left\|A\right\|^{l+1}\right|, \left|1 - \frac{\alpha}{\left\|A^{D}\right\|^{l+1}}\right|\right) < 1.$

Remark 1. We can significantly improve the convergence speed of this process using other iterative methods as Newton-Raphson method, Newton-Gregory interpolation formula, Hermite interpolation, ... (see e.g. [17]).

Example 2. We use the iterative algorithm previously developed to compute the Drazin inverse of the singular matrix:

$$A = \left(\begin{array}{rrr} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{array} \right).$$

It is easy to see that the minimal polynomial of A is given by $\lambda^3 - 3\lambda^2$, hence $\sigma(A) = \{0, 0, 3\}$ and $A^2 = 3A$. An easy computations show that ind(A) = 1 and that the Drazin inverse of A is given by $\frac{1}{9}A$. So we can choose $\alpha = 10^{-2}$ and l = 1, since $||A||^2 = 27$. Then the iterations are given by:

$$A_{0} = \alpha A = \begin{pmatrix} 0,01 & 0,01 & 0,01 \\ 0,01 & 0,01 & 0,01 \\ 0,01 & 0,01 & 0,01 \end{pmatrix},$$

$$A_{j+1} = BA_{j} + A_{0}, B = (I - \alpha A^{2}) = (I - 3A_{0}), j \in \mathbb{N}.$$

Thus,

$$B = (I - 3A_0) = \begin{pmatrix} 0,97 & -0,03 & -0,03 \\ -0,03 & 0,97 & -0,03 \\ -0,03 & -0,03 & 0,97 \end{pmatrix}.$$

and

$$A_{j} = \left(B^{j} + B^{j-1} + \dots + I\right) A_{0} = \sum_{m=0}^{j} B^{m} A_{0}, \ j \in \mathbb{N}$$

The matrix B is diagonalizable, $B = S^{-1}DS$, where S is a non-singular matrix and D is diagonal:

$$S = \begin{pmatrix} -0,3333 & 0,6667 & -0,3333 \\ -0,3333 & -0,3333 & 0,6667 \\ 0,3333 & 0,3333 & 0,3333 \end{pmatrix}, S^{-1} = \begin{pmatrix} -1 & -1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix},$$

and $D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0,91 \end{pmatrix}.$

$$B^{m} = S^{-1}D^{m}S, \ m \in \{0, 1, ..., j\},$$

$$A_{j} = S^{-1}\sum_{m=0}^{j}D^{m}SA_{0} = S^{-1} \begin{pmatrix} (j+1) & 0 & 0\\ 0 & (j+1) & 0\\ 0 & 0 & \alpha_{j} \end{pmatrix} SA_{0},$$

where
$$\alpha_j = \sum_{m=0}^{j} (0,91)^m = \frac{1-(0,91)^{j+1}}{0,09}, \ j \in \mathbb{N}.$$

$$A_j = \begin{pmatrix} -(j+1) & -(j+1) & \alpha_j \\ (j+1) & 0 & \alpha_j \\ 0 & (j+1) & \alpha_j \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0,01 & 0,01 & 0,01 \end{pmatrix} = \frac{\alpha_j}{100}A.$$
Since $\lim_{j \to \infty} \alpha_j = \sum_{m=0}^{\infty} (0,91)^m = \frac{100}{9}, \ it \ follows \ that \ \lim_{j \to \infty} A_j = \frac{1}{9}A = A^D.$

3 Continuity of the Drazin inverse of a matrix

The Drazin inverse of a matrix is not necessarily a continuous function of the elements of the matrix. In particular, It is easy to produce examples to show that Theorem 1 is not valid for the Drazin inverse (see [4]).

Example 3. 1) Let:

$$A_j = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & \frac{1}{j} \\ 0 & 0 & 0 \end{pmatrix}, \ A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}.$$

Then, $\lim_{j\to\infty} A_j = A$, $\lim_{j\to\infty} A_j^D = A^D$, but $rank(A_j) > rank(A)$, for all $j \in \mathbb{N}^*$. 2) Let:

$$A_j = \begin{pmatrix} \frac{1}{j} & 1 & 0 & 0\\ 0 & 0 & 0 & 0\\ 0 & 0 & 0 & 1\\ 0 & 0 & 0 & 0 \end{pmatrix}, \ A = \begin{pmatrix} 0 & 1 & 0 & 0\\ 0 & 0 & 0 & 0\\ 0 & 0 & 0 & 1\\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

Then,

Thus, $\lim_{j\to\infty} A_j = A$, $rank(A_j) = rank(A)$ and $ind(A_j) = ind(A)$ for all $j \in \mathbb{N}^*$, but $\lim_{j\to\infty} A_j^D \neq A^D$.

Define the core-rank of $A \in \mathbb{C}^{n \times n}$ as rank of the matrix A^k where k = ind(A). It is showed in [4] an analogous result, to that of Moore Penrose (Theorem 1), for the Drazin inverse of a square matrix.

Theorem 4. ([4]) Suppose that $A_j, A \in \mathbb{C}^{n \times n}$, $j \in \mathbb{N}$, are such that $\lim_{j \to \infty} A_j = A$. Then, $\lim_{j \to \infty} A_j^D = A^D$ if and only if there is $q \in \mathbb{N}$ such that core-rank of A_j is equal to core-rank of A for all $j \in \mathbb{N}$, $j \ge q$.

Similarly, from the Jordan canonical form for A_j and A, A = C + N, $A_j = C_j + N_j$, where $C, N, C_j, N_j \in \mathbb{C}^{n \times n}$, C and C_j are non-singular and N and N_j are nilpotent, for every $j \in \mathbb{N}$, it is immediate to give necessary and sufficient conditions for the continuity of the Drazin inverse of a matrix. If $\lim_{k \to \infty} A_j = A$,

$$\lim_{j \to \infty} A_j^D = A^D \iff \exists q \in \mathbb{N} : rank(C_j) = rank(C) \text{ for } j \ge q.$$

4 Remarkable properties and computational procedure for the GD-inverse

Recall that if $A \in \mathcal{B}(X)$, then a(A) and d(A), respectively the ascent and the descent of A, is the smallest non-negative integer k such that $\mathcal{N}(A^k) = \mathcal{N}(A^{k+1})$ and $\mathcal{R}(A^k) = \mathcal{R}(A^{k+1})$. If no such k exists, then $a(A) = \infty$ and $d(A) = \infty$. It is well known that if the ascent and the descent of an operator are finite, then they are equal. $A^D \in \mathcal{B}(X)$ is the Drazin inverse of $A \in \mathcal{B}(X)$ if $A^D A = AA^D$, $A^D AA^D = A^D$ and $AA^D A = A + Q$ where Q is a nilpotent operator on X. A^D is unique. The concept of Drazin invertible operators has been generalized by Koliha [9] by replacing the nilpotent operator Q in the equation $AA^D A = A + Q$ by a quasi-nilpotent operator. In this case, A^D is called a generalized Drazin inverse (GD-inverse) of A and noted A^{GD} . Invertible operators, right invertible operators and left invertible operators are GD-invertible operators. We define the Drazin index of A by:

$$ind(A) = \begin{cases} 0 & \text{if } A \text{ is invertible} \\ k & \text{if } Q = A \left(A^D A - I \right) \text{ is nilpotent of index } k \\ \infty & \text{if } Q = A \left(A^D A - I \right) \text{ is quasi-nilpotent.} \end{cases}$$

Note that a square matrix always has Drazin inverse. But, if X is an infinitedimensional complex Banach space, then it is well known that an operator $A \in \mathcal{B}(X)$ has a Drazin inverse A^D if and only if it has finite ascent and descent (in such a case, the index of A is equal to the ascent of A), or equivalently if and only if 0 is a pole of its resolvent operator, which is also equivalent to the fact that $A = R \oplus N$ where R is invertible and N is nilpotent. A has a GD-inverse if and only if 0 is an isolated point of its spectrum or $A = R \oplus Q$ where R is invertible and Q is quasi-nilpotent, or equivalently if and only if there is a bounded projection P on X (the generalized Drazin idempotent of A) such that $R = A_{|\mathcal{R}(P)}$ is invertible operator and $Q = A_{|N(P)}$ is quasi-nilpotent operator (see [[11], [9], [12], [14], [13]]). \oplus denotes the algebraic direct sum. Note that the GD-inverse A^{GD} of A, if it exists, is uniquely determined by $A^{GD} = R^{-1} \oplus 0$. Moreover, by the spectral mapping theorem we have that:

$$\sigma(A^{GD}) = \left\{\frac{1}{\lambda} : \lambda \in \sigma'(A)\right\} \cup \{0\}, \ \sigma'(A^{GD}) = \left\{\frac{1}{\lambda} : \lambda \in \sigma'(A)\right\}$$

and if r(A) > 0, then $dist(\sigma'(A), 0) = \frac{1}{r(A^{GD})}$, where dist is the distance between a bounded subset of \mathbb{C} and 0.

Example 4. 1) Every Drazin invertible operator is GD-invertible. It is also clear from the definition of a GD-inverse that every quasi-nilpotent operator is GD-invertible with a generalized Drazin inverse 0.

2) Every quasi-nilpotent operator which is not nilpotent (for example Volterra operator) is GD-invertible and cannot be Drazin invertible. Indeed, suppose that $A \in \mathcal{B}(X)$ is quasi-nilpotent but not nilpotent and Drazin invertible with $A^D = B$. We have seen before that A is GD-invertible with GD-inverse 0. By the uniqueness of the GD-inverse we must have that B = 0. Also, because A - ABA is nilpotent, we have that A is also nilpotent. This is a contradiction.

The following result gives an interesting characterization of Drazin invertible operators.

Proposition 2. ([9]) Let $A \in \mathcal{B}(X)$ and $k \in \mathbb{N}$, $k \ge 1$. Then the following assertions are equivalent:

- 1) A is Drazin invertible and ind(A) = k.
- 2) a(A) = d(A) = k.
- 3) The resolvent operator $(\lambda A)^{-1}$ has a pole of order k at $\lambda = 0$.

Example 5. Let's check that if $A \in \mathcal{B}(X)$ is normal, $A^*A = AA^*$, and if $0 \in iso\sigma(A)$, then A is Drazin invertible and ind(A) = 1. Indeed, if P is the spectral projection associated with 0. We know that A and P commute and then $A(\mathcal{R}(P)) \subseteq \mathcal{R}(P)$ and $\sigma(A_{|\mathcal{R}(P)}) = \{0\}$. On the other hand, since $A_{|\mathcal{R}(P)}$ is normal operator on $\mathcal{R}(P)$, we have $||A_{|\mathcal{R}(P)}|| = r(A_{|\mathcal{R}(P)}) = 0$, so it follows that AP = 0. The Laurent series expansion around 0 of the resolvent $(\lambda - A)^{-1}$ is given by:

$$(\lambda - A)^{-1} = \sum_{j=1}^{\infty} \frac{P_j}{\lambda^j} + \sum_{j=0}^{\infty} Q_j \lambda^j, \ 0 < |\lambda| < \epsilon$$

$$(11)$$

where the coefficients P_i and Q_i are given by the formulas:

$$P_j = \frac{1}{2\pi i} \oint_{0 < |\lambda| < \epsilon} \lambda^{j-1} (\lambda - A)^{-1} d\lambda \text{ and } Q_j = \frac{1}{2\pi i} \oint_{0 < |\lambda| < \epsilon} \lambda^{-j-1} (\lambda - A)^{-1} d\lambda.$$
(12)

It follows from (12), immediately using the functional calculus, that:

$$P_1 = P \text{ and } P_j = A^{j-1}P, \ j \in \mathbb{N}^*,$$

hence 0 is a simple pole of $(\lambda - A)^{-1}$. Proposition 2 shows that A is Drazin invertible and ind(A) = 1.

Drazin inverses are not symmetric in general. Let $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \in \mathbb{C}^{2 \times 2}$, A is Drazin invertible with $A^D = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$, but $(A^D)^D = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \neq A$. Our next result gives the expression of the element $(A^{GD})^{GD}$.

Theorem 5. Let $A \in \mathcal{B}(X)$. Suppose that A is GD-invertible and that P is the generalized Drazin idempotent of A. Then $(A^{GD})^{GD} = A(I - P)$.

Proof. Suppose that A is generalized Drazin invertible and that P is the generalized Drazin idempotent of A. If A is invertible then P = 0 and the result obviously holds.

If $0 \in iso\sigma(A)$, then P is the spectral projection of A corresponding to 0 and $P = I - A^{GD}A$. We show that B = A(I - P) is the generalized Drazin inverse of A^{GD} . Using the fact that AP = PA, we have that $A^{GD}B = A^{GD}A(I - P) = A(I - P)A^{GD} = BA^{GD}$. We also have that:

$$BA^{GD}B = A(I-P)A^{GD}A(I-P) = A(I-P)A^{GD}A(A^{GD}A)$$
$$= A(I-P)(A^{GD}AA^{GD})A = A(I-P)A^{GD}A$$
$$= A(I-P)(I-P) = A(I-P) = B,$$

and

$$\begin{split} A^{GD} - A^{GD}BA^{GD} &= A^{GD} - A^{GD}A(I-P)A^{GD} = A^{GD} - A^{GD}A(A^{GD}A)A^{GD} \\ &= A^{GD} - (A^{GD}AA^{GD})AA^{GD} = A^{GD} - A^{GD}AA^{GD} = 0 \end{split}$$

is quasi-nilpotent. Hence, $(A^{GD})^{GD} = B = A(I - P)$. This completes the proof.

As 0 is a simple pole of $(\lambda - A)^{-1}$ if and only if AP = 0, we obtain:

Corollary 1. Let $A \in \mathcal{B}(X)$ and $0 \in iso\sigma(A)$. Then $(A^{GD})^{GD} = A$ if and only if 0 is a simple pole of $(\lambda - A)^{-1}$.

In the following we give a representation theorem for the Drazin inverse of a linear operator in Banach space and the corresponding error bound.

Theorem 6. Let $A \in \mathcal{B}(X)$ be Drazin invertible of index k and $\mathcal{R}(A^k)$ is closed. Define $\widetilde{A} = (A^k A^{*2k+1} A^{k+1})_{|\mathcal{R}(A^k)}$. If Ω is an open set such that $\sigma\left(\widetilde{A}\right) \subset \Omega \subset [0, \infty[$ and $(S_j(x))_{j\in\mathbb{N}}$ is a sequence of continuous real valued functions on Ω with $\lim_{j\to\infty} S_j(x) = \frac{1}{x}$ uniformly on $\sigma\left(\widetilde{A}\right)$, then:

$$A^{D} = \lim_{j \to \infty} S_j\left(\widetilde{A}\right) A^k A^{*2k+1} A^k.$$

Furthermore, for any $\varepsilon > 0$, there is an operator norm $\|.\|_*$ on X such that:

$$\frac{\left\|S_{j}\left(\widetilde{A}\right)A^{k}A^{*2k+1}A^{k}-A^{D}\right\|_{*}}{\left\|A^{D}\right\|_{*}} \leq \max_{x \in \sigma(\widetilde{A})}\left|S_{j}(x)x-1\right|+\mathcal{O}\left(\varepsilon\right).$$

Proof. It's clear that $\sigma\left(\widetilde{A}\right) = \sigma\left(A^k A^{*2k+1} A^{k+1}\right) = \sigma\left(\left(A^{2k+1}\right)^* \left(A^{2k+1}\right)\right) \subset]0, \infty[$, since \widetilde{A} is positive and boundedly invertible. Using functional calculus, we have:

$$\lim_{j \to \infty} S_j\left(\widetilde{A}\right) = \widetilde{A}^{-1}.$$

It then follows from [2] that:

$$\lim_{j \to \infty} S_j\left(\widetilde{A}\right) A^k A^{*2k+1} A^k = \widetilde{A}^{-1} A^k A^{*2k+1} A^k = A^D.$$

To obtain the error bound, we note that:

$$A^{k}A^{*2k+1}A^{k} = \widetilde{A}A^{D},$$

$$S_{j}\left(\widetilde{A}\right)A^{k}A^{*2k+1}A^{k} - A^{D} = \left(S_{j}\left(\widetilde{A}\right)\widetilde{A} - I\right)A^{D}.$$

We also know that for any $\varepsilon > 0$, one can define a new norm $\|.\|_*$ on X with the formula:

$$||x||_{*} = \sqrt{\sum_{j=0}^{m} \left(\frac{||A^{j}x||}{M^{j}}\right)^{2}},$$

where $M = r(A) + \varepsilon$ and $m \in \mathbb{N}$ has been chosen as the first integer such that $||A^m||^{1/m} < M$. It is easy to see that this norm is equivalent to the original norm and it induces a norm on $\mathcal{B}(X)$ such that $||A||_* < r(A) + \varepsilon$. Thus,

$$\begin{split} \left\| S_{j}\left(\widetilde{A}\right) A^{k} A^{*2k+1} A^{k} - A^{D} \right\|_{*} &\leq \left\| S_{j}\left(\widetilde{A}\right) \widetilde{A} - I \right\|_{*} \left\| A^{D} \right\|_{*} \\ &\leq \left(\max_{x \in \sigma\left(\widetilde{A}\right)} \left| S_{j}(x) x - 1 \right| + \mathcal{O}\left(\varepsilon\right) \right) \left\| A^{D} \right\|_{*}. \end{split}$$

Now we explain the Euler-Knopp Method for computational of the Drazin inverse of a bounded operator and the way to get the corresponding error bound. First we need the following result concerning lower and upper bounds for $\sigma(\widetilde{A})$.

Lemma 2. Let $A \in \mathcal{B}(X)$ be Drazin invertible of index k and $\mathcal{R}(A^k)$ is closed. Then, for all $\lambda \in \sigma(\widetilde{A})$:

$$\frac{1}{\left\| \left(A^{2k+1}\right)^{\dagger} \right\|^{2}} \le \lambda \le \|A\|^{4k+2}.$$

Proof. For all $\lambda \in \sigma\left(\widetilde{A}\right)$, $\lambda > 0$ and $\lambda \in \sigma\left(\left(A^{2k+1}\right)^*\left(A^{2k+1}\right)\right)$. Furthermore, it's clear that $ind\left(\left(A^{2k+1}\right)^*A^{2k+1}\right) = 1$ and

$$\frac{1}{\lambda} \in \sigma\left(\left(\left(A^{2k+1}\right)^* A^{2k+1}\right)^\dagger\right) = \sigma\left(\left(A^{2k+1}\right)^\dagger \left(\left(A^{2k+1}\right)^{\dagger *}\right)\right).$$

Thus,

$$\frac{1}{\lambda} \le \left\| \left(A^{2k+1} \right)^{\dagger} \left(\left(A^{2k+1} \right)^{\dagger *} \right) \right\| = \left\| \left(A^{2k+1} \right)^{\dagger} \right\|^2 \text{ and } \lambda \ge \frac{1}{\left\| \left(A^{2k+1} \right)^{\dagger} \right\|^2}.$$

On the other hand, since $\left\| \left(A^k A^{*2k+1} A^{k+1} \right)_{|\mathcal{R}(A^k)} \right\| \leq \left\| A^k A^{*2k+1} A^{k+1} \right\|$, we obtain $\left\| \widetilde{A} \right\| \leq \left\| A \right\|^{4k+2}$ so what $\lambda \leq \left\| \widetilde{A} \right\| \leq \left\| A \right\|^{4k+2}$ for all $\lambda \in \sigma\left(\widetilde{A} \right)$.

Consider now the sequence $(S_p(x))_{p\in\mathbb{N}}$ and the set E_{α} , $\alpha > 0$, defined respectively in (5) and (6). By Lemma 2, we get $\sigma\left(\widetilde{A}\right) \subseteq \left]0, \|A\|^{4k+2}\right]$. So, if we choose the parameter α , $0 < \alpha < \frac{2}{\|A\|^{4k+2}}$ such that $\sigma\left(\widetilde{A}\right) \subseteq \left]0, \|A\|^{4k+2}\right] \subset E_{\alpha}$, then we obtain the following representation of the Drazin inverse A^D of A:

$$A^{D} = \alpha \sum_{j=0}^{\infty} \left(I - \alpha A^{k} A^{*2k+1} A^{k+1} \right)^{j} A^{k} A^{*2k+1} A^{k}.$$

Setting $A_j = \alpha \sum_{m=0}^{j} (I - \alpha A^k A^{*2k+1} A^{k+1})^m A^k A^{*2k+1} A^k$, we have the following iterative procedure for the Drazin inverse:

$$A_0 = \alpha A^k A^{*2k+1} A^k$$
 and $A_{j+1} = \left(I - \alpha A^k A^{*2k+1} A^{k+1}\right) A_j, \ j \in \mathbb{N}.$

Therefore, $\lim_{j \to \infty} A_j = A^D$. For the error bound, we note that from (9) and (10), we have $|xS_j(x) - 1| = |1 - \alpha x|^{j+1} \leq \beta^{j+1} \xrightarrow{j \to \infty} 0$, if $x \in \sigma\left(\widetilde{A}\right)$, $0 < \alpha < \frac{2}{\|A\|^{4k+2}}$

and $\beta = \max\left\{ \left| 1 - \alpha \|A\|^{4k+2} \right|, \left| 1 - \frac{\alpha}{\|(A^{2k+1})^{\dagger}\|^2} \right| \right\} < 1$. It follows from the above inequality and Theorem 6, the error bound:

$$\frac{\left\|A_{j}-A^{D}\right\|_{*}}{\left\|A^{D}\right\|_{*}} \leq \beta^{j+1} + \mathcal{O}\left(\varepsilon\right), \ \varepsilon > 0.$$

Note that this approximation generalizes to infinite-dimensional case the result obtained on the square matrices in Theorem 3.

Example 6. Let $A \in \mathcal{B}(X)$ be selfadjoint, $A^* = A$, and $0 \in iso\sigma(A)$. Then A has closed range and is Drazin invertible with ind(A) = 1. Let's use the iterative procedure developed previously with $0 < \alpha < \frac{2}{\|A\|^6}$ and $\beta = \max\left\{\left|1 - \alpha \|A\|^6\right|, \left|1 - \frac{\alpha}{\|(A^3)^{\dagger}\|^2}\right|\right\} < 1$. So, $\lim_{j \to \infty} A_j = A^D$ where $A_0 = \alpha A^5$, $A_{j+1} = (I - \alpha A^6) A_j$, $j \in \mathbb{N}$, and the error bound $\frac{\|A_j - A^D\|_*}{\|A^D\|_*} \leq \beta^{j+1} + O(\varepsilon), \varepsilon > 0$.

5 Continuity of the GD-Drazin inverse

Drazin inversion is not continuous in general, we illustrate this in the following example.

Example 7. Let $A \in \mathcal{B}(l_2)$ be a weighted shift with weight sequence:

$$0, 0, -1, 0, 0, -1, 0, 0, -1, \dots$$

so that A is nilpotent of index 3. Then A is Drazin invertible and with $A^D = 0$. Let $A_j = A + \frac{1}{i}I$, for all $j \in \mathbb{N}^*$. Then, for each $j \in \mathbb{N}^*$:

$$A_j (jI - j^2A + j^3A^2) = (jI - j^2A + j^3A^2) A_j = I.$$

Thus A_i is invertible and hence Drazin invertible with:

$$A_j^D = A_j^{-1} = (jI - j^2A + j^3A^2), j \in \mathbb{N}^*.$$

It is clear that $A_j \longrightarrow A$ as $j \to \infty$ in $\mathcal{B}(l_2)$, but the unbounded sequence $\left(A_j^D\right)_{j \in \mathbb{N}^*}$ does not converge to $A^D = 0$.

Rakocevic investigate in [16] the continuity of the Drazin inverse of a bounded linear operator on Banach space, i.e. the continuity of the maps $A \longrightarrow A^D$ and $A \longrightarrow A^{GD}$, $A \in B(X)$, he generalized the continuity result of [7] to Drazin inverse in the following way. Let $(A_j)_{j\in\mathbb{N}}$ be a sequence in $\mathcal{B}(X)$, and let $\lim_{j\to\infty} A_j = A$. Suppose that A and A_j , have Drazin inverses A^D and A_j^D respectively. Then the following conditions are equivalent:

(1)
$$\lim_{j \to \infty} A_j^D = A^D$$
. (2) $\sup_{j \in \mathbb{N}} \left\| A_j^D \right\| < \infty$. (3) $\lim_{j \to \infty} A_j^D A_j = A^D A$.

Furthermore, by virtue of Banach-Steinhaus theorem, we can easily deduce, as a generalization, an equivalent result when $(A_j)_{j \in \mathbb{N}}$ converges to A strongly.

It is interesting to study the continuity of the GD-inverse. We are now ready to present the main result of this section, it is due to Koliha and Rakocevic [10], nevertheless, the proof below is direct and of a technical nature.

Theorem 7. Let $(A_j)_{j \in \mathbb{N}}$ be a sequence in $\mathcal{B}(X)$, and let $\lim_{j \to \infty} A_j = A$. Suppose that A and A_j have generalized Drazin inverses A^{GD} and A_j^{GD} , and let P and P_j be the spectral projections corresponding to 0, of A and A_j , respectively, for every $j \in \mathbb{N}$. Then the following conditions are equivalent:

(i)
$$\lim_{j \to \infty} A_j^{GD} = A^{GD}.$$

(ii)
$$\sup_{j \in \mathbb{N}} \left\| A_j^{GD} \right\| < \infty.$$

(iii)
$$\sup_{j \in \mathbb{N}} \left\| r\left(A_j^{GD}\right) \right\| < \infty.$$

(iv)
$$\inf_{j \in \mathbb{N}} dist(\sigma'(A_j), 0) > 0.$$

(v) There exists an r > 0 such that $\widetilde{B}(0,r) \subseteq \rho(A) \cap \bigcap_{j=0}^{\infty} \rho(A_j)$, where $\widetilde{B}(0,r)$ is the open ball excluding the center 0 and with radius r. (vi) $\lim_{j\to\infty} A_j^{GD}A_j = A^{GD}A$. (vii) $\lim_{j\to\infty} P_j = P$.

Proof. (i) \Longrightarrow (ii). Follows from the fact that convergence implies boundedness. (ii) \Longrightarrow (iii). Suppose that (ii) holds. Since $r\left(A_{j}^{GD}\right) \leq \left\|A_{j}^{GD}\right\| \leq \sup_{j \in \mathbb{N}} \left\|A_{j}^{GD}\right\| < \infty$, for all $j \in \mathbb{N}$, we obtain that $\sup_{j \in \mathbb{N}} r\left(A_{j}^{GD}\right) \leq \sup_{j \in \mathbb{N}} \left\|A_{j}^{GD}\right\| < \infty$.

(iii) \implies (iv). Suppose that $k = \sup_{j \in \mathbb{N}} r\left(A_j^{GD}\right) < \infty$. We distinguish the following three cases:

Case I: $r\left(A_{j}^{GD}\right) = 0$ for all $j \in \mathbb{N}$. Then $\sigma\left(A_{j}^{GD}\right) = \{0\}$ and hence $\sigma\left(A_{j}\right) = \{0\}$, so $dist(\sigma'(A_{j}), 0) = \infty$, for all $j \in \mathbb{N}$. It then follows that $\inf_{j \in \mathbb{N}} dist(\sigma'(A_{j}), 0) = \infty > 0$.

Case II: If $r\left(A_{j}^{GD}\right) > 0$ for all $j \in \mathbb{N}$, then k > 0 and $\left(r\left(A_{j}^{GD}\right)\right)^{-1} \geq k^{-1}$. Hence, $r\left(A_{j}^{GD}\right) = r\left(A_{j}^{GD}A_{j}A_{j}^{GD}\right) \leq \left(r\left(A_{j}^{GD}\right)\right)^{2}r\left(A_{j}\right)$, so that $r\left(A_{j}\right) \geq \left(r\left(A_{j}^{GD}\right)\right)^{-1} \geq k^{-1} > 0$, for all $j \in \mathbb{N}$. Or, for all $j \in \mathbb{N}$, $dist(\sigma'(A_{j}), 0) = \left(r\left(A_{j}^{GD}\right)\right)^{-1} \geq k^{-1} > 0$, and hence $\inf_{j \in \mathbb{N}} dist(\sigma'(A_{j}), 0) \geq k^{-1} > 0$.

Case III: There is at least one $j \in \mathbb{N}$ such that $r\left(A_{j}^{GD}\right) > 0$ and possibly some other j' for which $r\left(A_{j'}^{GD}\right) = 0$. By case II, we have that $dist(\sigma'(A_j), 0) = \left(r\left(A_{j}^{GD}\right)\right)^{-1} \geq k^{-1} > 0$ for all $j \in \mathbb{N}$ satisfying $r\left(A_{j}^{GD}\right) > 0$. By case I,

 $dist(\sigma'(A_{j'}), 0) = \infty$ for all $j' \in \mathbb{N}$ such that $r\left(A_{j'}^{GD}\right) = 0$. Let $k_j = dist(\sigma'(A_j), 0)$. Then,

$$\inf \left\{ dist(\sigma'(A_j), 0) : j \in \mathbb{N} \right\} = \inf \left\{ k_j : j \in \mathbb{N} \text{ satisfies } r\left(A_j^{GD}\right) > 0 \right\} \ge k^{-1} > 0,$$

hence the result follows.

(iv) \Longrightarrow (v). Suppose that $M = \inf_{j \in \mathbb{N}} dist(\sigma'(A_j), 0) > 0$. Let $r = \min(m, M)$ where $m = dist(\sigma'(A), 0)$. By the choice of r and the fact that $\bigcap_{j=0}^{\infty} \rho(A_j) = \mathbb{C} \setminus \bigcup_{j=0}^{\infty} \sigma(A_j)$, we have that $\widetilde{B}(0, r) \subseteq \bigcap_{j=0}^{\infty} \rho(A_j)$ and $\widetilde{B}(0, r) \subseteq \rho(A)$. (v) \Longrightarrow (vi). Suppose that there exists an r > 0 such that $\widetilde{B}(0, r) \subseteq \rho(A) \cap \bigcap_{j=0}^{\infty} \rho(A_j)$ and show that $A_j^{GD}A_j \longrightarrow A^{GD}A$ as $j \to \infty$.

If A is invertible, so A_j is too for all sufficiently large $j \in \mathbb{N}$ and $A_j^{GD} = A_j^{-1} \longrightarrow A^{-1} = A^{GD}$ as $j \to \infty$. By the continuity of multiplication in $\mathcal{B}(X)$, it follows that $A_j^{GD}A_j \longrightarrow A^{GD}A$ as $j \to \infty$.

Suppose now that $0 \in iso\sigma(A)$ and P is the spectral projection of A corresponding to 0. Let:

$$\Omega_1 = \left\{ \lambda \in \mathbb{C} : |\lambda| < \frac{r}{3} \right\} \text{ and } \Omega_2 = \left\{ \lambda \in \mathbb{C} : |\lambda| > \frac{2r}{3} \right\}$$

By hypothesis, Ω_1 and Ω_2 are open sets containing $\{0\}$ and $\sigma'(A)$ respectively, and hence $\Omega = \Omega_1 \cup \Omega_2$ is an open set containing $\sigma(A)$. Define $f : \Omega \longrightarrow \mathbb{C}$ by:

$$f(\lambda) = \begin{cases} 1 & \text{if } \lambda \in \Omega_1 \\ 0 & \text{if } \lambda \in \Omega_2 \end{cases}$$

Then, f is holomorphic on Ω and P = f(A). The spectral projection P_j of A_j corresponding to 0, might be 0 for several $j \in \mathbb{N}$. Also, by hypothesis, Ω_2 is an open set containing $\sigma'(A_j)$ for all $j \in \mathbb{N}$, so that $P_j = f(A_j)$ for all $j \in \mathbb{N}$. It follows that $P_j = f(A_j) \longrightarrow f(A) = P$ as $j \to \infty$ and since $A^{GD} = (A + P)^{-1}(I - P)$ and $A_j^{GD} = (A_j + P_j)^{-1}(I - P_j)$, we have $A_j^{GD}A_j \longrightarrow A^{GD}A$ as $j \to \infty$. From the above, it is clear that (vi) is equivalent to assertion (vii).

Finally, we prove that (vii) \Longrightarrow (i). Suppose that (vii) holds. Since $A_j + P_j$ and A + P are invertible in $\mathcal{B}(X)$, for all $j \in \mathbb{N}$, and $(A_j + P_j) \longrightarrow A + P$ as $j \to \infty$, it then follows that $(A_j + P_j)^{-1} \longrightarrow (A + P)^{-1}$ as $j \to \infty$. Hence, by the continuity of multiplication in $\mathcal{B}(X)$, $A_j^{GD} = (A_j + P_j)^{-1}(I - P_j) \longrightarrow (A + P)^{-1}(I - P) = A^{GD}$ as $j \to \infty$. This completes the proof.

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